

PROJECT PORTFOLIO

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HI I AM KURT AXL

Graduated:

Bachelor of Science in Computer Engineering

University of Batangas Lipa Campus

Web Technologies:

Python | Fast API | NextJs |
MySQL | Git/GitHub

Design Technologies:

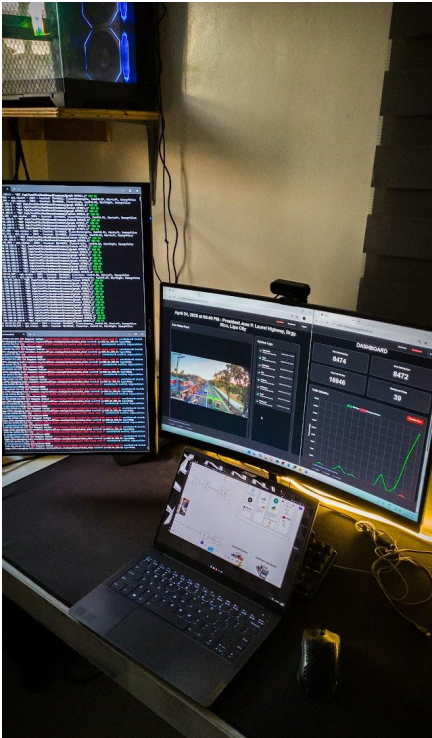
Figma | Photoshop | Premiere
Pro | Davinci Resolve | FL
Studio

Internship Experience:

Data Developer Support - *Taisei Electronics*
Philippines



Thesis Project - Alert V2



This project was built with Yolo v11, Next Js and Fast API

The Goal of the Project is to analyze and get traffic information using the computer vision model. It allows simple data traffic analysis using its dashboard.

March 22, 2025 - Brgy. Sico Lipa City

34:21

Camera 01

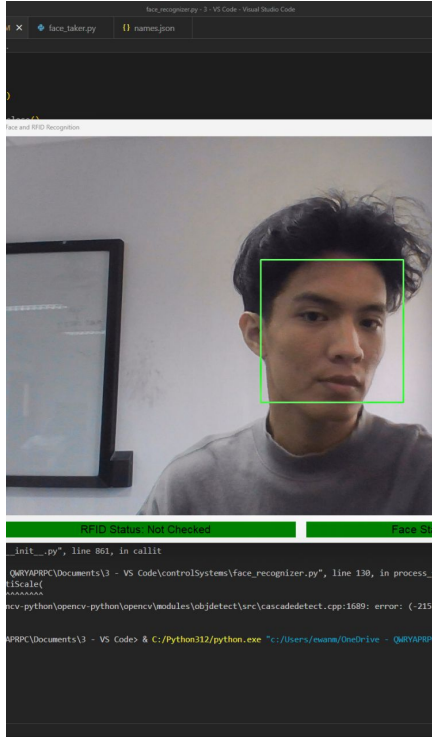
System Logs

- Ambulance: less than a min. Ambulance detected at the
- Ambulance: less than a min. Ambulance detected at the
- Ambulance: less than a min. Ambulance detected at the
- Ambulance: less than a min. Ambulance detected at the
- Ambulance: less than a min. Ambulance detected at the
- Ambulance: less than a min. Ambulance detected at the
- Car: less than a minute ago Car detected at the gate
- Car: less than a minute ago Car detected at the gate
- Ambulance: less than a min. Ambulance detected at the
- Car: less than a minute ago Car detected at the gate
- Car: less than a minute ago Car detected at the gate
- Ambulance: less than a min. Ambulance detected at the



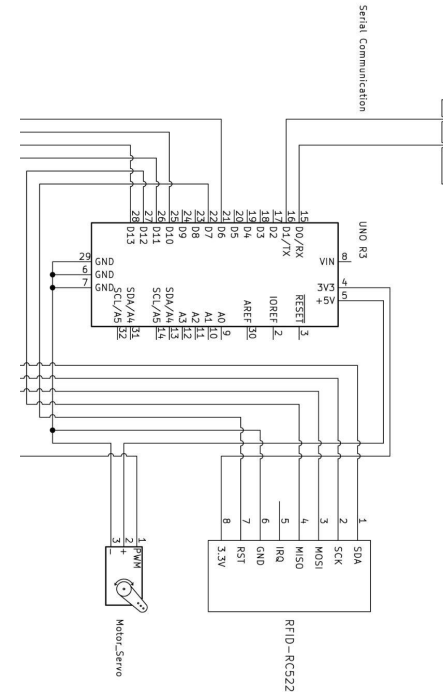
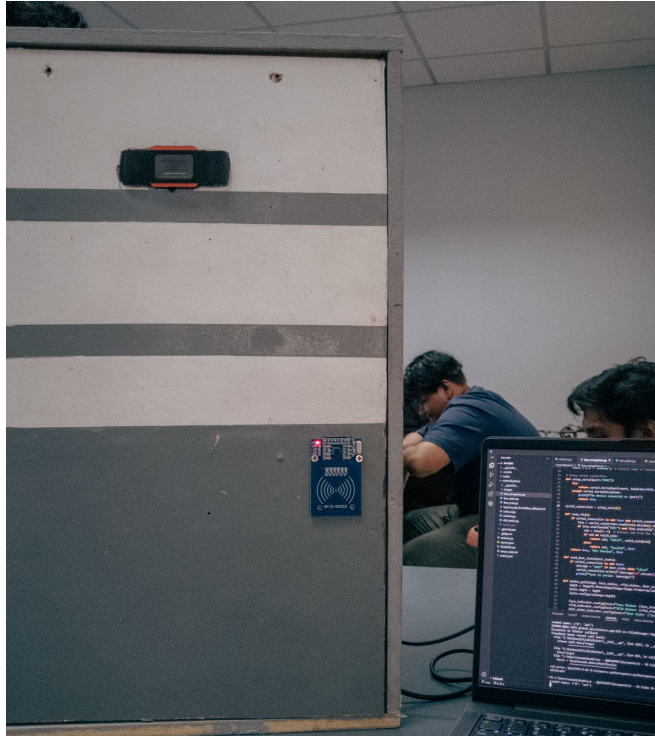
Trained using google collab, and run on a custom linux computer.

Smart Door Project - Embedded System + Computer Vision



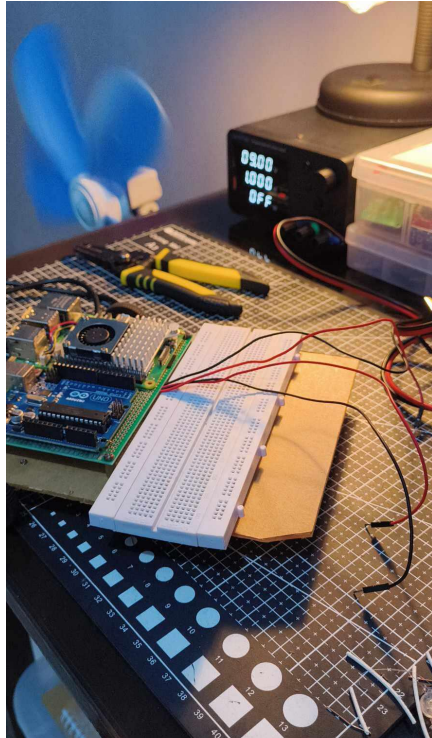
The system used Haarscascade algorithm to detect faces.

The Goal of the project is to make a smart security door that allows the user to have 2 factor authentication using face and an rfid module.



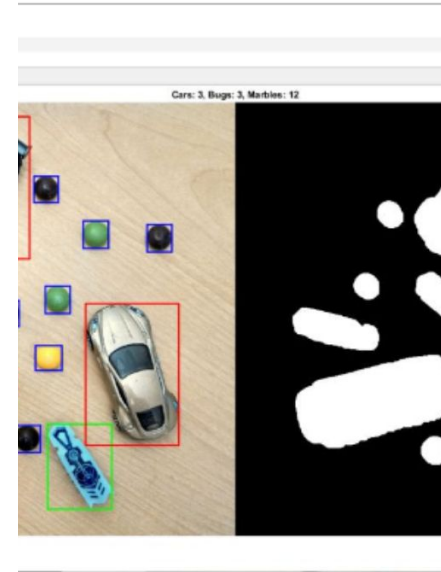
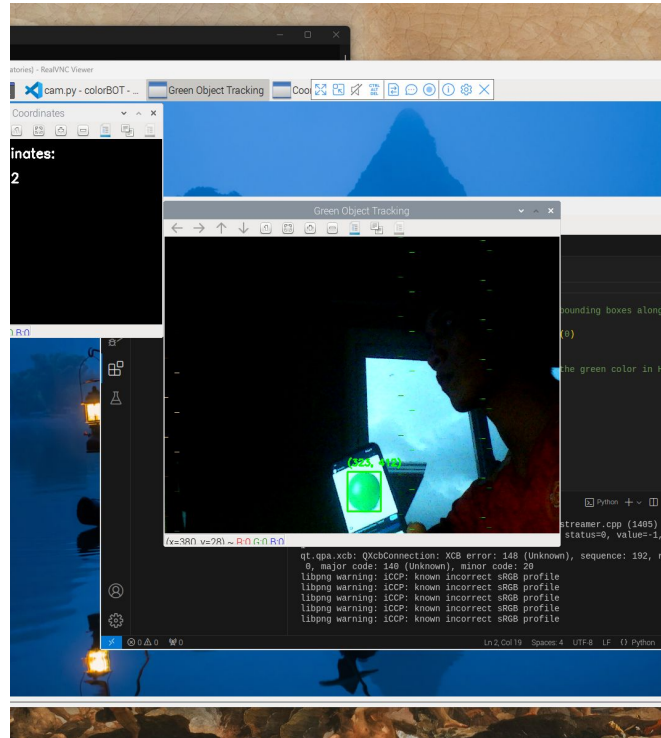
It utilizes the arduino serial communication to connect with the laptop

Color Detection Robot - Embedded + Computer Vision



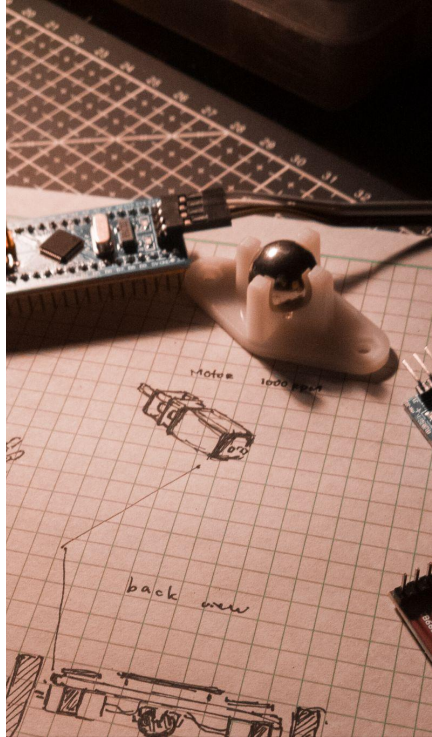
Powered by Raspberry PI and arduino

The Project Goal is to make robot that follow a certain color using the color threshold method.



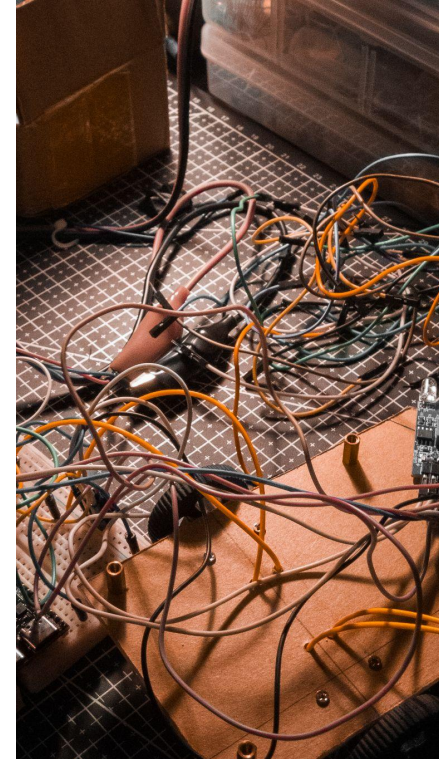
It uses image color tresholding to detect the ball and follow it accordingly

Mazebot - Autonomous Maze Solving Robot



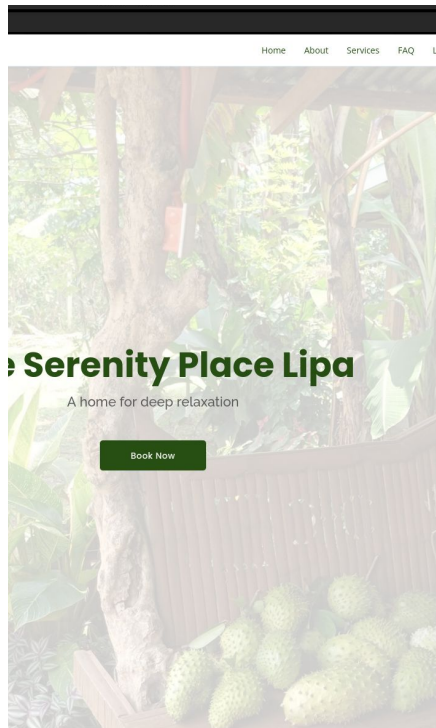
Powered by: ESP 32 and
programmed under Arduino IDE

The goal of the Project is to make a automatic maze solving robot by using algorithm to solve the maze.



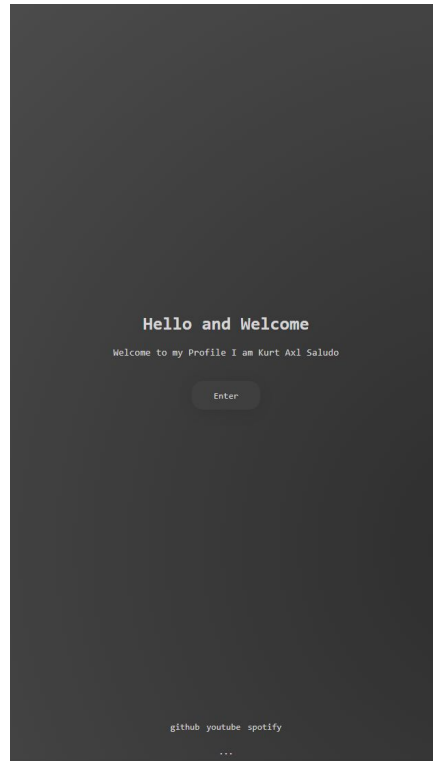
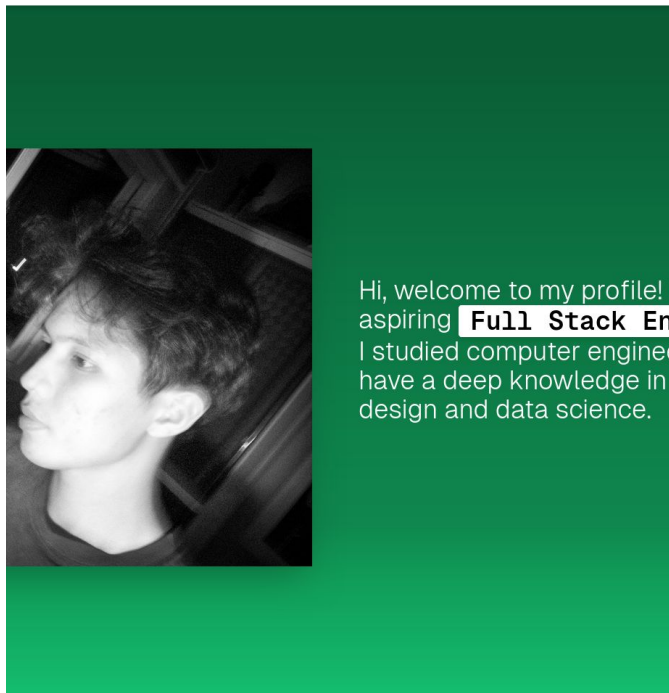
Uses Left Side bias algorithm to
solve the maze.

Websites



Several Websites derived design inspirations from architecture design

This collection of projects showcases my knowledge about, design and website development



Also there are several website purposely built for freelance clients



Thank You

Questions?
Please reach out to
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